

# SANMOTION F2

2-PHASE STEPPING SYSTEMS

## Small Size 2-Phase Stepping Motor

**14mm sq. (.55 inch sq.)**



### Features

**Industry's Top Small 14 mm sq. and Light Weight 28 g**

The information is current as of December, 2011. The above data is based on our own research, collected among 2-phase stepping motors for industrial use.

**High Torque**

### Application

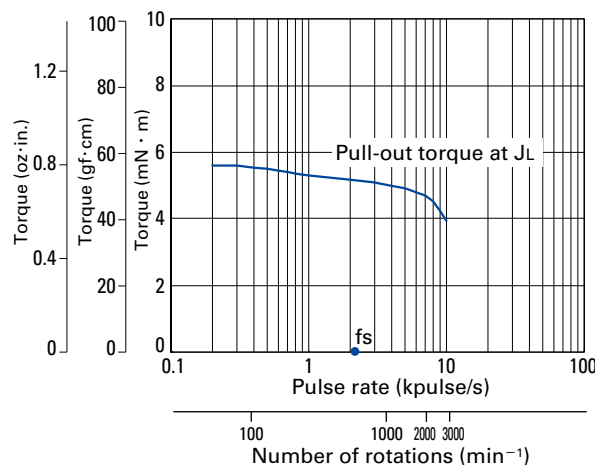
Devices where mountable space is quite limited such as an electric gripper and an electric cylinder

### Specification

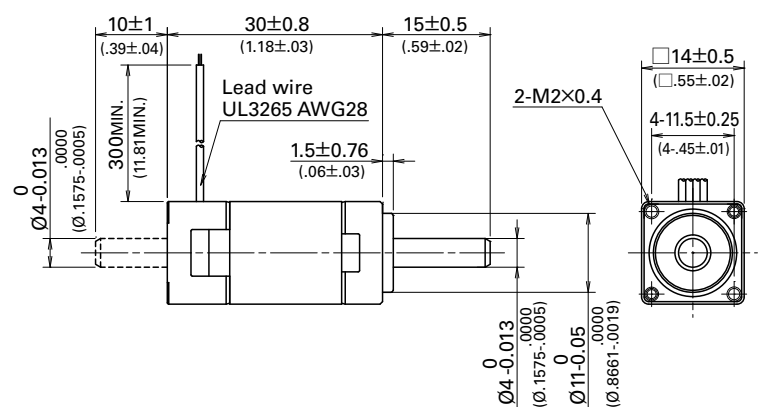
1.8° /Step Bipolar winding

Model		Holding torque at 2-phase energization [N·m (oz·in) MIN.]	Rated current [A/phase]	Wiring resistance [Ω /phase]	Winding inductance [mH/phase]	Rotor inertia [ $\times 10^{-4}$ kg·m <sup>2</sup> (oz·in <sup>2</sup> ) ]	Mass [kg(lbs)]
Single shaft	Double shafts						
SH2141-5541	SH2141-5511	0.0065 (0.92)	0.3	21	4.2	0.00058 (0.0032)	0.028 (0.062)

### Pulse rate-torque characteristics



### Dimensions [unit : mm (inch)]



- Constant current circuit
- Source voltage: 24 V DC
- Operating current: 0.3A/phase
- 2-phase energization (full-step)
- $J_L=0.01 \times 10^{-4}$  kg·m<sup>2</sup> (pulley balancer method)
- fs: No load maximum starting pulse rate

The data are measured under the drive condition of our company. The drive torque may vary depending on the accuracy of customer-side equipment.



2-phase stepping motor

# 42mm sq.( 1.65inch sq. )

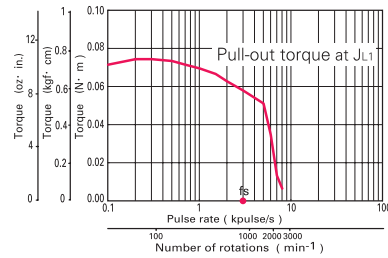
SS242 □  
1.8° / step Bipolar winding

**Bipolar winding · Lead wire type**

Model		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass ( Weight )
Single shaft	Double shafts	[N· m( oz· in ) MIN.]	A/phase	Ω /phase	mH/phase	[× 10 <sup>-4</sup> kg· m <sup>2</sup> ( oz· in <sup>2</sup> )]	[kg( lbs )]
SS2421-5041	-5011	0.083 ( 11.75 )	1	3.5	1.2	0.015 ( 0.082 )	0.07 ( 0.15 )
SS2422-5041	-5011	0.186 ( 26.33 )	1	5.4	2.9	0.028 ( 0.153 )	0.14 ( 0.31 )
SS2423-5041	-5011	0.240 ( 33.98 )	1	7.3	5	0.038 ( 0.208 )	0.20 ( 0.44 )

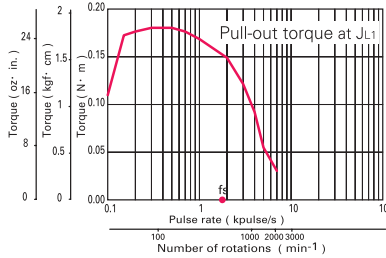
■ **Pulse rate-torque characteristics**

• **SS2421-50** □ □



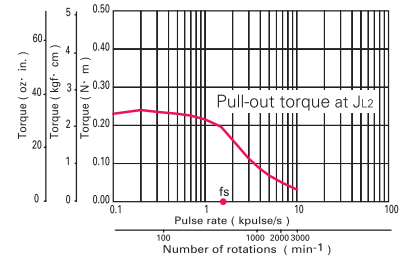
Constant current circuit  
Source voltage : DC24V· operating current : 1A/phase,  
2-phase energization( full-step )  
 $J_{L1} = [ 0.33 \times 10^{-4} \text{kg} \cdot \text{m}^2 ( 1.80 \text{oz} \cdot \text{in}^2 )$  inertia of rubber coupling is in cluded ]  
 $J_{L2} = [ 0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 ( 5.14 \text{oz} \cdot \text{in}^2 )$  inertia of rubber coupling is in cluded ]  
fs: No load maximum starting pulse rate

• **SS2422-50** □ □



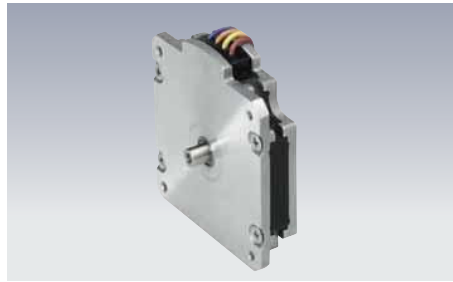
Constant current circuit  
Source voltage : DC24V· operating current : 1A/phase,  
2-phase energization( full-step )  
 $J_{L1} = [ 0.33 \times 10^{-4} \text{kg} \cdot \text{m}^2 ( 1.80 \text{oz} \cdot \text{in}^2 )$  inertia of rubber coupling is in cluded ]  
 $J_{L2} = [ 0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 ( 5.14 \text{oz} \cdot \text{in}^2 )$  inertia of rubber coupling is in cluded ]  
fs: No load maximum starting pulse rate

• **SS2423-50** □ □



Constant current circuit  
Source voltage : DC24V· operating current : 1A/phase,  
2-phase energization( full-step )  
 $J_{L1} = [ 0.33 \times 10^{-4} \text{kg} \cdot \text{m}^2 ( 1.80 \text{oz} \cdot \text{in}^2 )$  inertia of rubber coupling is in cluded ]  
 $J_{L2} = [ 0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 ( 5.14 \text{oz} \cdot \text{in}^2 )$  inertia of rubber coupling is in cluded ]  
fs: No load maximum starting pulse rate

The data are measured under the drive condition of our company. The drive torque may vary depending on the accuracy of customer-side equipment.



2-phase stepping motor

# 50mm sq.( 1.97inch sq. )

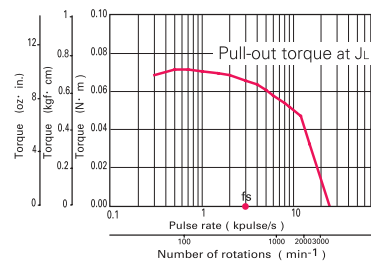
SS250 □  
1.8° / step Bipolar winding

**Bipolar winding · Lead wire type**

Model		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass ( Weight )
Single shaft	Double shafts	[N· m( oz· in ) MIN.]	A/phase	Ω /phase	mH/phase	[× 10 <sup>-4</sup> kg· m <sup>2</sup> ( oz· in <sup>2</sup> )]	[kg( lbs )]
<b>SS2501-5041</b>	<b>-5011</b>	0.1 ( 14.16 )	1	4.5	1.8	0.026 ( 0.142 )	0.09 ( 0.20 )
<b>SS2502-5041</b>	<b>-5011</b>	0.215 ( 30.44 )	1	5.9	3.2	0.049 ( 0.268 )	0.15 ( 0.33 )

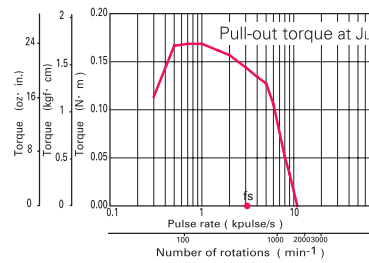
## ■ Pulse rate-torque characteristics

• **SS2501-50** □ □



Constant current circuit  
Source voltage : DC24V· operating current : 1A/phase,  
1-2-phase energization( half-step )  
JL = [ 0.01x10<sup>-4</sup>kg· m<sup>2</sup>( 0.055 oz· in<sup>2</sup> ) Pulley balancer  
system ]  
fs: No load maximum starting pulse rate

• **SS2502-50** □ □



Constant current circuit  
Source voltage : DC24V· operating current : 1A/phase,  
1-2-phase energization( half-step )  
JL = [ 0.01x10<sup>-4</sup>kg· m<sup>2</sup>( 0.055 oz· in<sup>2</sup> ) Pulley balancer  
system ]  
fs: No load maximum starting pulse rate

The data are measured under the drive condition of our company. The drive torque may very depending on the accuracy of customer-side equipment.